

Homomorphisms

Objectives:

1. Define homomorphisms
2. Show homomorphic transformations
3. Show that isomorphism is a special case of homomorphism

Recall: Isomorphism

- $f: V \rightarrow W$ is isomorphic if V and W have the same dimension and
1. it is closed under addition and scalar multiplication
 2. it is bijective (one-to-one and onto).

* Homomorphism

A structure preserving map between two vector spaces that does not have to be the same size.

Let V and W be vector spaces and $f: V \rightarrow W$.

A function f is called a homomorphism (also known as a linear map)

if for all $\vec{v}_1, \vec{v}_2 \in V$ and scalars $c \in \mathbb{R}$:

- $f(\vec{v}_1 + \vec{v}_2) = f(\vec{v}_1) + f(\vec{v}_2)$
- $f(c\vec{v}_1) = cf(\vec{v}_1)$.

If $f: V \rightarrow W$ is bijective, then it is isomorphic.

Examples:

1.
$$f\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = \begin{bmatrix} x \\ x+y+z \end{bmatrix}$$

Let $f: \mathbb{R}^3 \rightarrow \mathbb{R}^2$.

Let $\begin{bmatrix} x_1 \\ y_1 \\ z_1 \end{bmatrix}, \begin{bmatrix} x_2 \\ y_2 \\ z_2 \end{bmatrix} \in \mathbb{R}^3$ and $c_1, c_2 \in \mathbb{R}$.

$$\begin{aligned} f\left(c_1 \begin{bmatrix} x_1 \\ y_1 \\ z_1 \end{bmatrix} + c_2 \begin{bmatrix} x_2 \\ y_2 \\ z_2 \end{bmatrix}\right) &= f\left(\begin{bmatrix} c_1 x_1 \\ c_1 y_1 \\ c_1 z_1 \end{bmatrix} + \begin{bmatrix} c_2 x_2 \\ c_2 y_2 \\ c_2 z_2 \end{bmatrix}\right) \\ &= f\left(\begin{bmatrix} c_1 x_1 + c_2 x_2 \\ c_1 y_1 + c_2 y_2 \\ c_1 z_1 + c_2 z_2 \end{bmatrix}\right) \end{aligned}$$



$$= \begin{bmatrix} C_1 x_1 + C_2 x_2 \\ C_1 x_1 + C_2 x_2 + C_1 y_1 + C_2 y_2 + C_1 z_1 + C_2 z_2 \end{bmatrix}$$

$$= \begin{bmatrix} C_1 x_1 + C_2 x_2 \\ C_1 x_1 + C_1 y_1 + C_1 z_1 + C_2 x_2 + C_2 y_2 + C_2 z_2 \end{bmatrix}$$

$$= \begin{bmatrix} C_1 x_1 \\ C_1 x_1 + C_1 y_1 + C_1 z_1 \end{bmatrix} + \begin{bmatrix} C_2 x_2 \\ C_2 x_2 + C_2 y_2 + C_2 z_2 \end{bmatrix}$$

$$= C_1 \begin{bmatrix} x_1 \\ x_1 + y_1 + z_1 \end{bmatrix} + C_2 \begin{bmatrix} x_2 \\ x_2 + y_2 + z_2 \end{bmatrix}$$

$$= C_1 f\left(\begin{bmatrix} x_1 \\ y_1 \\ z_1 \end{bmatrix}\right) + C_2 f\left(\begin{bmatrix} x_2 \\ y_2 \\ z_2 \end{bmatrix}\right) \quad \leftarrow \text{this shows closure under addition and scalar multiplication}$$

So, f is homomorphic.

$$2. f\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Let $f: \mathbb{R}^3 \rightarrow \mathbb{R}^2$.

Let $\begin{bmatrix} x_1 \\ y_1 \\ z_1 \end{bmatrix}, \begin{bmatrix} x_2 \\ y_2 \\ z_2 \end{bmatrix} \in \mathbb{R}^3$ and $C_1, C_2 \in \mathbb{R}$.

$$f\left(C_1 \begin{bmatrix} x_1 \\ y_1 \\ z_1 \end{bmatrix} + C_2 \begin{bmatrix} x_2 \\ y_2 \\ z_2 \end{bmatrix}\right) = f\left(\begin{bmatrix} C_1 x_1 + C_2 x_2 \\ C_1 y_1 + C_2 y_2 \\ C_1 z_1 + C_2 z_2 \end{bmatrix}\right) \quad \begin{matrix} \leftarrow \text{"x"} \\ \leftarrow \text{"y"} \\ \leftarrow \text{"z"} \end{matrix}$$

$$= \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \leftarrow \text{always } \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\text{So, if } \begin{bmatrix} x_1 \\ y_1 \\ z_1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \text{ then } f\left(\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \neq \begin{bmatrix} 0 \\ 0 \end{bmatrix}.$$

Thus, f is not homomorphic because $\vec{0} \in \mathbb{R}^3$ must map to $\vec{0} \in \mathbb{R}^2$.

* A linear map sends the zero vector to the zero vector.

Example: $\begin{bmatrix} x \\ y \end{bmatrix} \xrightarrow{f} \begin{bmatrix} x \\ 0 \end{bmatrix}$ is a homomorphism

because you can show closure under addition and scalar multiplication
and $\begin{bmatrix} 0 \\ 0 \end{bmatrix} \mapsto \begin{bmatrix} 0 \\ 0 \end{bmatrix}$. $\leftarrow \vec{0}$ maps to $\vec{0}$

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* A homomorphism is determined by its action on a basis.

If V is a vector space with basis $\{\vec{\beta}_1, \dots, \vec{\beta}_n\}$,
if W is a vector space, and if $\vec{w}_1, \dots, \vec{w}_n \in W$,
then there exist a homomorphism from V to W
sending each $\vec{\beta}_i$ to $\vec{w}_i$ and it is unique.

* Linear Extension

Let V and W be vector spaces and let $B = \{\vec{\beta}_1, \dots, \vec{\beta}_n\}$
be a basis for V .

A function defined on that basis $f: B \rightarrow W$ is extended linearly
to a function $\hat{f}: V \rightarrow W$ if for all $\vec{v} \in V$ such that
 $\vec{v} = c_1 \vec{\beta}_1 + \dots + c_n \vec{\beta}_n$, the action map is
 $\hat{f}(\vec{v}) = c_1 f(\vec{\beta}_1) + \dots + c_n f(\vec{\beta}_n)$.

Example: Let $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ with basis $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$.

$$f\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} -1 \\ 1 \end{bmatrix}, \quad f\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} -4 \\ 4 \end{bmatrix} \quad \leftarrow \text{defined action}$$

$$\begin{aligned} f\left(\begin{bmatrix} 3 \\ -2 \end{bmatrix}\right) &= f\left(3 \begin{bmatrix} 1 \\ 0 \end{bmatrix} - 2 \begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = 3f\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) - 2f\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) \\ &\quad \leftarrow \text{linear combination} \\ &= 3 \begin{bmatrix} -1 \\ 1 \end{bmatrix} - 2 \begin{bmatrix} -4 \\ 4 \end{bmatrix} \\ &= \begin{bmatrix} -3 + 8 \\ 3 - 8 \end{bmatrix} \\ &= \begin{bmatrix} 5 \\ -5 \end{bmatrix} \end{aligned}$$

* A linear map from a space into itself $f: V \rightarrow V$ is a linear transformation.

Example: Rotation Transformations

Let $f_\theta: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a linear map that rotates
vectors in $\mathbb{R}^2$ back in $\mathbb{R}^2$ counterclockwise by θ .



